

ROBOT CONTROL METHOD AND ROBOT CONTROLLER APPLYING THE METHOD

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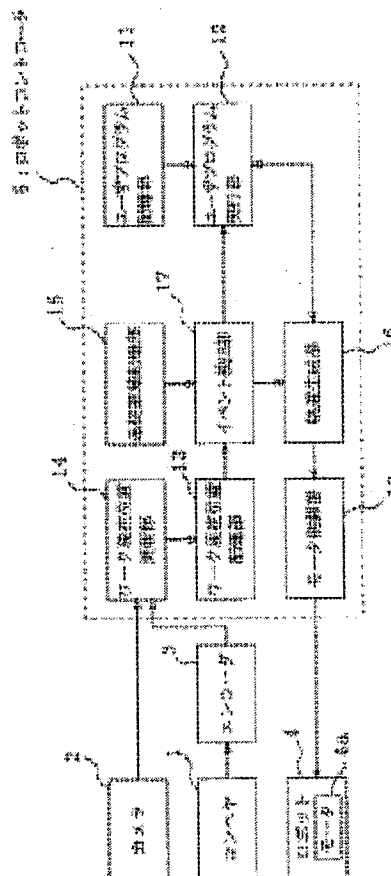
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Abstract of JP 2002192486 (A)

PROBLEM TO BE SOLVED: To provide a robot control method and a robot controller capable of reducing arithmetic operation quantity independent of a moving passage of a work in arithmetically operating a present position of the work with the movement of a conveyor and describing the operation and intuitively teaching relative to the work. **SOLUTION:** The present position of the work is sequentially renewed by a coordinate system of the conveyor 1 so that the trajectory of the robot 4 for following the work is generated by converting the position of the work from the coordinate system of the conveyor 1 to the coordinate system of the robot 4.



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